Semester	Fall 2021
Course Number Course Title	Technical Elective MATLAB-Simscape for Engineering Applications
Instructor	Ping C. Sui, Ph.D. Office: 4-223 E-Mail: <u>ping.sui@scupi.cn</u>
Teaching Assistant	ТВА
Office Hours	Tuesday 1:00-5:00PM Wednesday 1:00-5:00PM
Lecture Time/Room	Thursday 13:50-16:25 Teaching Building 1 A-108
Prerequisites	 Engineering 0011 and/or prior MATLAB fundamental training At least junior-level per SCUPI engineering disciplines Mechanical Engineering
Textbook (Optional)	 Russell, K., Shen, Q., Sodhi, R.S., 2019, Kinematics and Dynamics of Mechanical Systems - Implementation in MATLAB and Simmechanics, CRC Press, Boca Raton, FL Magrab, E.B., Azarm, S., Balachandran, B., Duncan, J.H., Herold, K.E., Walsh, G.C., 2011, An Engineer's Guide to MATLAB, Prentice Hall, Upper Saddle River, NJ
Course Description	This is a project-based course rather than a topic-based course, and students will learn the network-based programming, computational, and problem solving skills needed to complete the projects rather than progressing through a typical programming text.
	 This class is about Developing solution algorithms for solving governing equations in single- or multiphysical domains, Mostly linear/nonlinear ODE's, and A few PDE's Applying MATLAB Simscape libraries in developing physical models and solving the subsequent engineering analyses Most physical models will be dynamic motion analysis for mechanical systems This class is not about learning MATLAB programming, Simulink block diagrams, or control algorithms.
Class Outline	
I. MATLAB Funda a. Polynoi b. Solving II. Motion Analysis	mentals mial and Curve-Fitting Nonlinear Differential Equations s of Planar Mechanisms

- a. Review of Complex Number
- b. Vector Loop Equation of Planar Mechanisms
- c. Motion Analysis of Planar Mechanisms
- d. Numerical Methods for Motion Analysis

- e. MATLAB Nonlinear Solver for Motion Analysis
- III. Simscape Fundamental
 - a. Simscape and Simulink
 - b. Simscape Fundamental Library
 - c. Application Examples
- IV. SimMechanics and SimMultibody
 - a. Single- and Multi-DOF Dynamic System Analysis
 - b. Dynamic Analysis of Close-Loop Mechanisms
 - c. Analysis of Geartrain Systems
- V. Application Example: Vehicle Driveline Modeling
- VI. Application Example: Introduction to Robotic Manipulator
- VII. Preview of SimHydraulics

In-Class Workshops	Hands- Purpos lecturir	-on pra se is to ng.	actice prom	s to be note ir	e giver n-class	n durin discus	ig the ossions	class t and ke	hrougl eep stu	nout tł Jdents	ne sem in-syr	nester. nc with	n cours	e material during
Lab Assignments	Will be Due Da Late as Unfore	e distrik ay: 11:(ssignme eseeabl	buted 00 AN ent w le em	each ⁄I on tl vill not ergen	week he day be aco cies w	after t of the cepteo ill be c	he cla: e next d. lealt w	ss. class vith on	a case	e-by-ca	ase ba	sis.		
Final Project	Hands-on, independent task assignment Details will be furnished later Expected deliverables: Developed project model Written final report ~10-minute Presentation 													
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Class Attendance	Studen Early is no late	its are s on tin er than	expe ne, or the c	cted to n time lass st	o atter is late arting	nd eve e. As a time.	ry clas courte	s perio esy to v	od. your fe	ellow c	lassm	ates, k	e punc	ctual and arrive

Academic Honesty	All of us are equally responsible for ensuring a fair and positive learning environment. Students are permitted to discuss homework assignments together, but should do their own work when preparing a problem solution.
	All exams are to be completed without unauthorized assistance. Any student caught cheating on an assignment or exam will receive disciplinary action, up to and including receiving a grade of "F" for the course.